## **Izzat Mukhanov**

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## Summary

•	Software Engineer with 8+ years of full-time professional experience Passionate about tackling and simplifying complex problems Strong analytical, organizational and communication skills	
•	Master's degree in Robotics, Control, Applied Informatics from <u>ÉCN</u>	2012 - 2014
	Work Experience	
•	<ul> <li>Amazon: Software Engineer &amp; Tech Lead</li> <li>Prime Air: Autonomous 30 min delivery system by drones</li> <li>Successfully designed, implemented and delivered: <ul> <li>Vehicle simulator that supports time accelerations.</li> <li>Scalable backend for thousands of vehicles.</li> <li>Vehicle-agnostic autonomous path planning system.</li> </ul> </li> <li>Significant contributions: <ul> <li>Influenced multiple teams on testing framework design and implementation.</li> <li>Simplified various flows/architecture/implementations across Prime Air orga</li> <li>Deployment, maintenance and improvement of multiple AWS web services.</li> <li>Coverage analytics platform to choose areas of operations.</li> </ul> </li> </ul>	2016 – now
•	<b>INRIA</b> : Software developer Development and distribution of a cross-platform library <u>libpointing</u> to get raw events from pointing devices and apply transfer functions	2014 – 2016
•	<b>SSD software solutions</b> : Mobile developer iOS applications and Cocos2d games	2011 – 2012
Professional Skills		
•	Knowledgeable: • Java, Python, C++	

- Distributed systems, AWS ecosystem, Software Design and Testing, DDD
- Path Planning, Kinematic Modeling, Discrete Optimization, Simulations
- Familiar:
  - Scala, MATLAB, Objective-C, Pharo, C#.NET, PHP, SQL, etc.
  - Kafka, Spark, Websockets, Netty, Protobuf
  - 3D modeling and visualization, OpenGL, OpenCV, ROS (Robot Operating System)
  - Background in Control, Computer Vision, Machine Learning

## Miscellaneous

- Master's Thesis on "Pedestrian Detection and Tracking system" [thesis] [video]
- OpenSYMORO: An open-source software for Symbolic Modelling of Robots [paper]
- Fluent in English and French, native in Russian and Uzbek